

# Analyzing PDV Spectrograms with Likelihood Methods



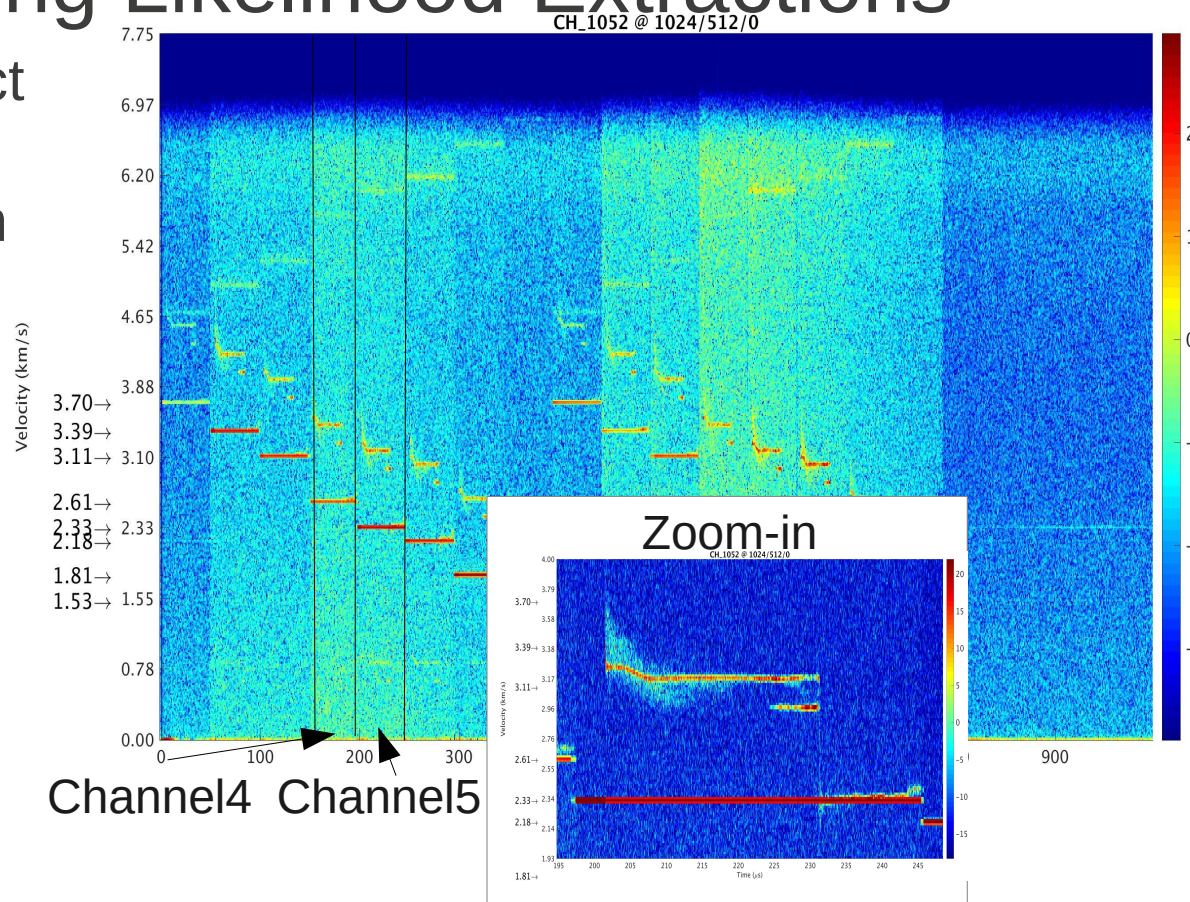
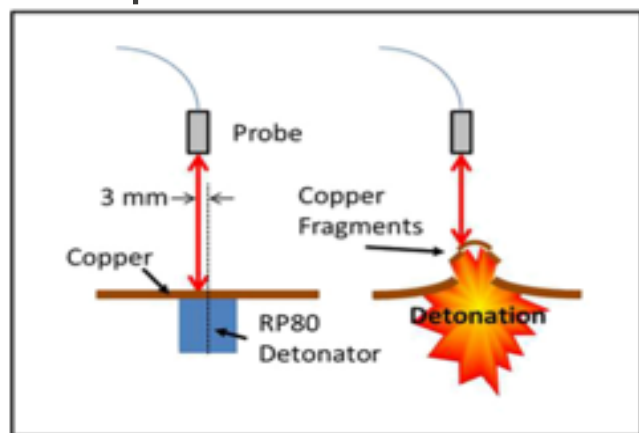
- J. Patrick Harding
- 6/8/16

# Contents

- Applying Likelihood Analysis to PDV Data
- Statistical Vetting of the Analysis
- Testing the Analysis Results with Synthetic Data

# Data for Testing Likelihood Extractions

Test data has copper object moving at “single velocity” with all channels pointed in the same direction at the same place

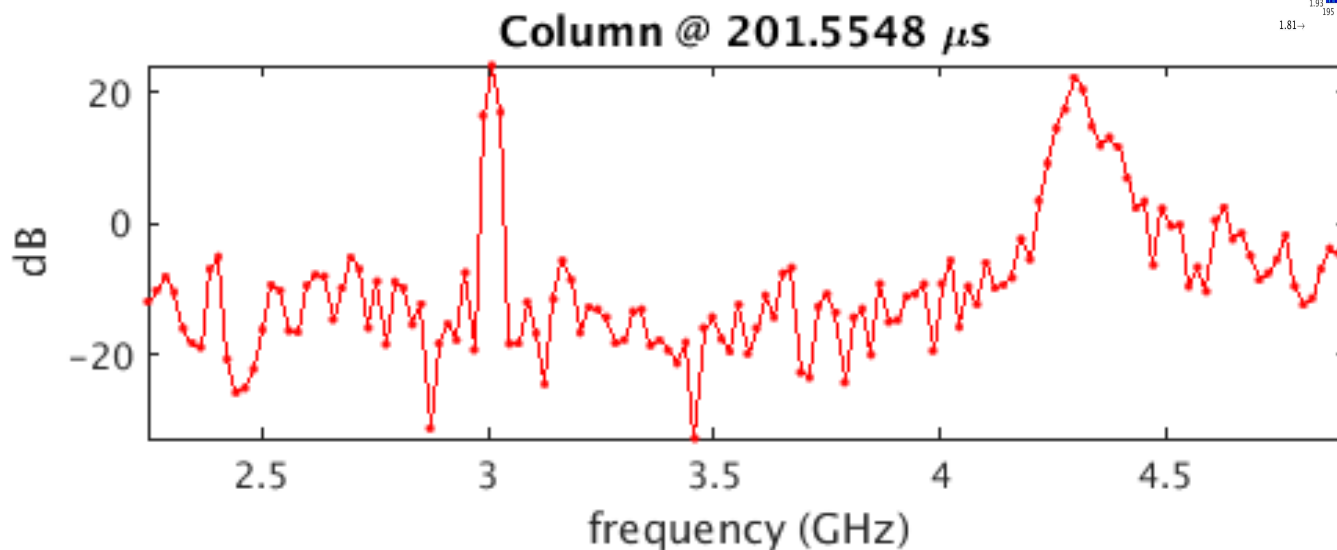
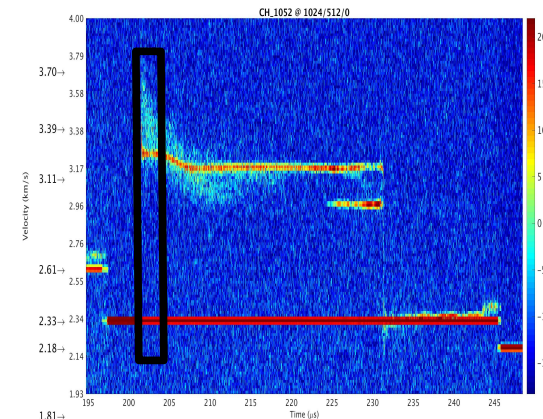


- Gen 3 Evaluation Shots, STL, May 2015 \*
- Comparing the analysis of two channels will give a quantitative size of the statistical error bars of the analysis

\* Credit: Ed Daykin, Chan Jung, Mike Pena, Abel Diaz, Marylesa Howard, Ben Valencia, Benji Stone, Kirk Miller

# Sample Lineout from the Data

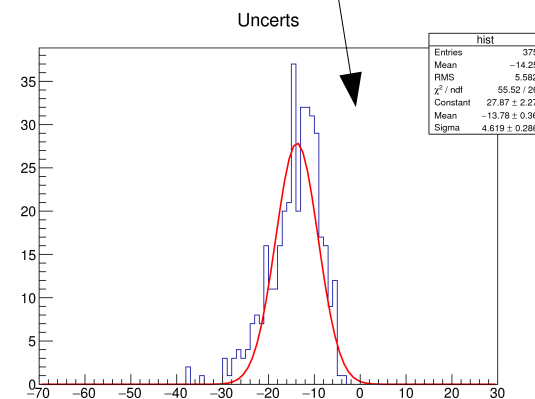
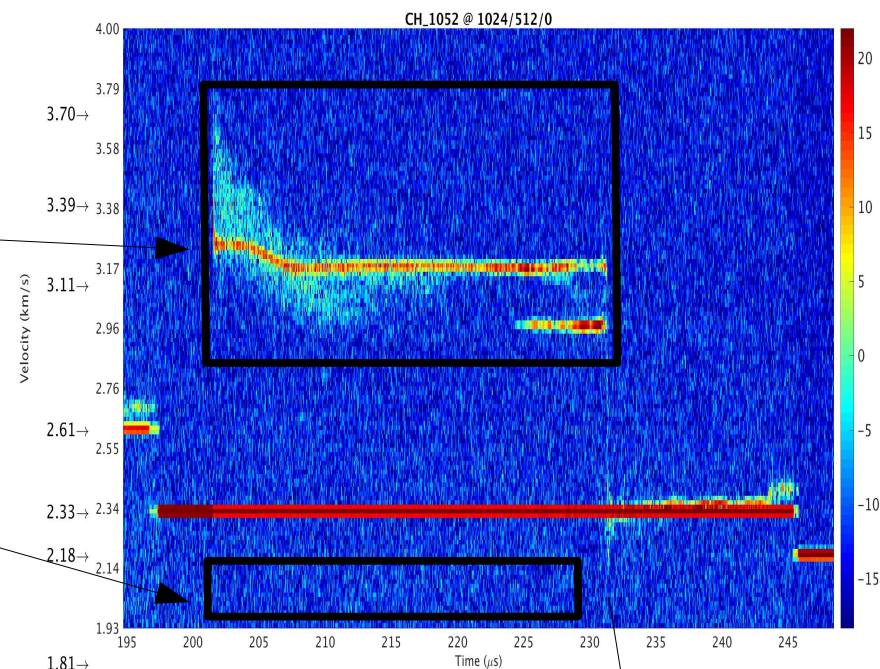
- Single slice in time
- Can have differing levels of noise
- Multiple peaks → Multiple surfaces
- Wide peaks → Ejecta





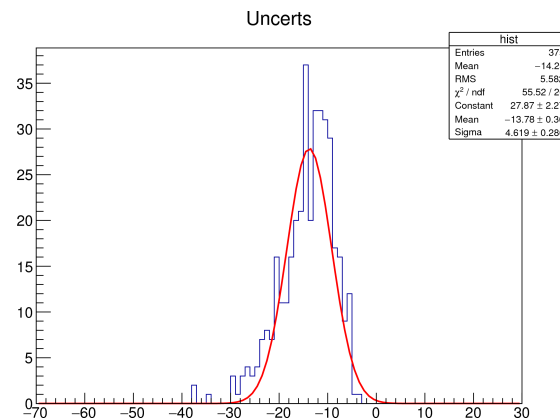
# Likelihood Velocity Extractions

- Two ROIs per channel
  - Data region
    - All signals you want to test
    - Can be large
  - Background region
    - No signals
    - For statistics
- Assume Gaussian statistics
  - Fits background fluctuations well
- Model includes:
  - Free noise level
  - Multiple peaks (surfaces) with free widths



# The Background

- Region far from any signal
- Fluctuations fit to a gaussian in dB-space
  - Width determines statistical significance of features in data region
  - Peak location determines nominal signal-free background level



# Statistics with Maximum Likelihood (1)

- *If* background is Gaussain noise (and it does)
  - *Then* the log-likelihood test statistic (TS) is analogous to a chi-squared
  - Method works for arbitrary noise distribution, too

- The logarithm of the likelihood is

$$\ln(\text{pdf}) = -\ln(\Sigma) - 0.5 \ln(2\pi) - 0.5 \cdot (\text{dB}_i - \mu(v_i))^2 / \Sigma^2$$

summed over all frequency (velocity) bins  $i$

- for background with Gaussian width  $\Sigma$
- and for signal model  $\mu(v)$
- Gaussian Statistics:  $p(n_i; \mu_i, \Sigma) = \frac{1}{\sqrt{2\pi}\Sigma} \exp\left[-\frac{(n_i - \mu_i)^2}{2\Sigma^2}\right]$

## Statistics with Maximum Likelihood (2)

- Get LL for two models to compare (e.g. signal or not).
- Maximize each LL over the free parameters
- $TS^{\max} = 2 * (LL_1^{\max} - LL_0^{\max})$ 
  - Related to significance that there is a velocity (or other parameter) to be extracted
  - If TS is large (considering the number of added parameters), then the parameters exist
  - Roughly,  $\sqrt{TS} \sim \#$  of sigmas of signal
- Lower TS threshold gives fainter features
  - But finds more “false peak” fluctuations, too
  - $TS \sim 10$  balances these two extremes well

# Statistics with Maximum Likelihood (2)

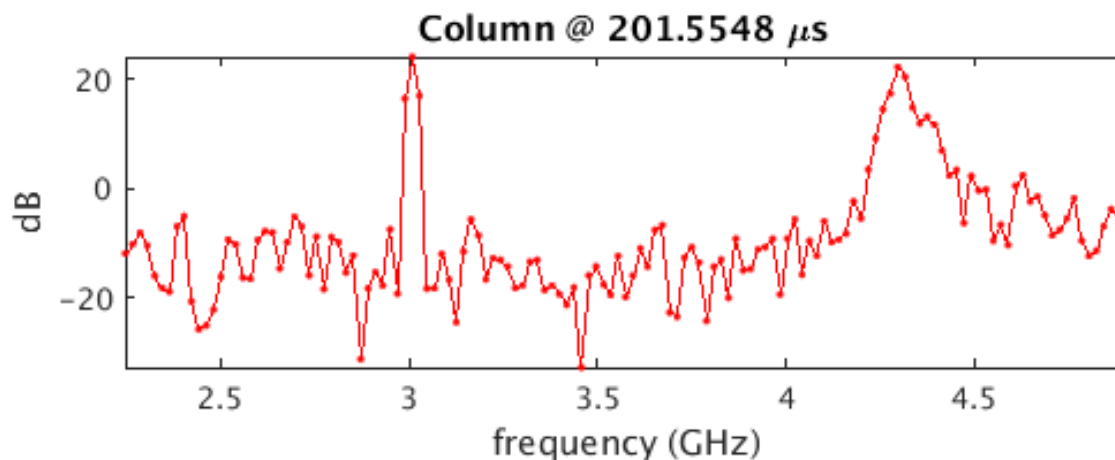
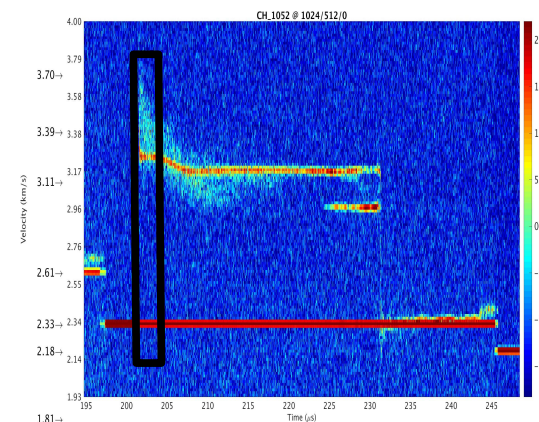
- Get LL for two models to compare (e.g. signal or not).
- Maximize each LL over the free parameters
- TS (Test Statistic)
  - Relates to the likelihood ratio (max)
  - If there is a velocity (or other parameter) that is being tested
  - If TS is large (considered significant), then the parameter is likely to be non-zero
  - Roughly,  $\sqrt{\text{TS}} \sim \# \text{ of sigmas of signal}$
- Lower TS threshold gives fainter features
  - But finds more “false peak” fluctuations, too
  - TS~10 balances these two extremes well

*Finds all model parameters and uncertainties on all the parameters*

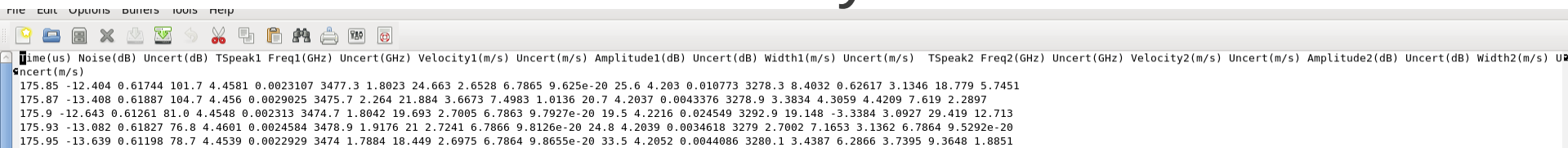


# The Signal Model

- Each timeslice is considered separately
- Models fit as Gaussians in dB(frequency)
- Model checks:
  - Is there a true peak in frequency?
  - Is the peak wider than the baseline?
  - Is the noise level different than in background ROI?
  - Is there a second peak in frequency?



# Extracted Velocity Information

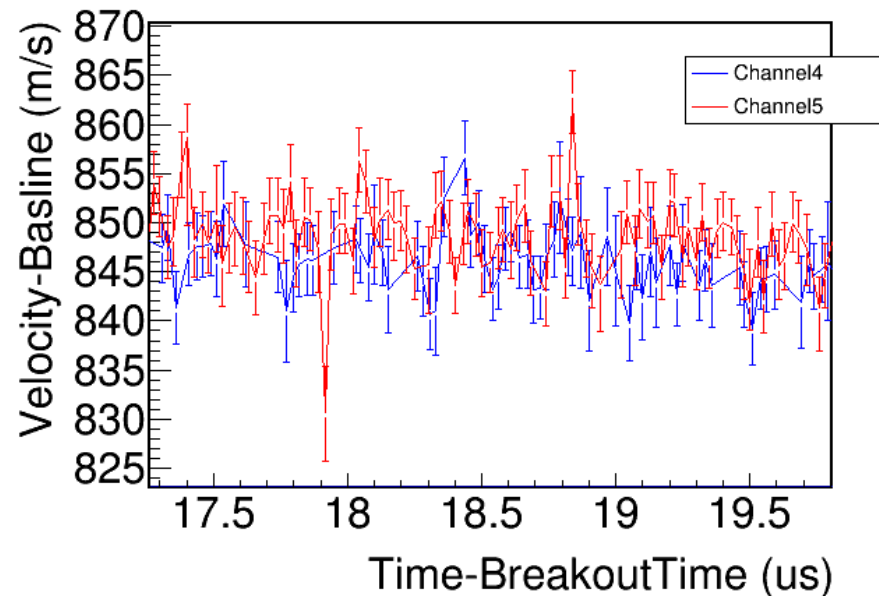
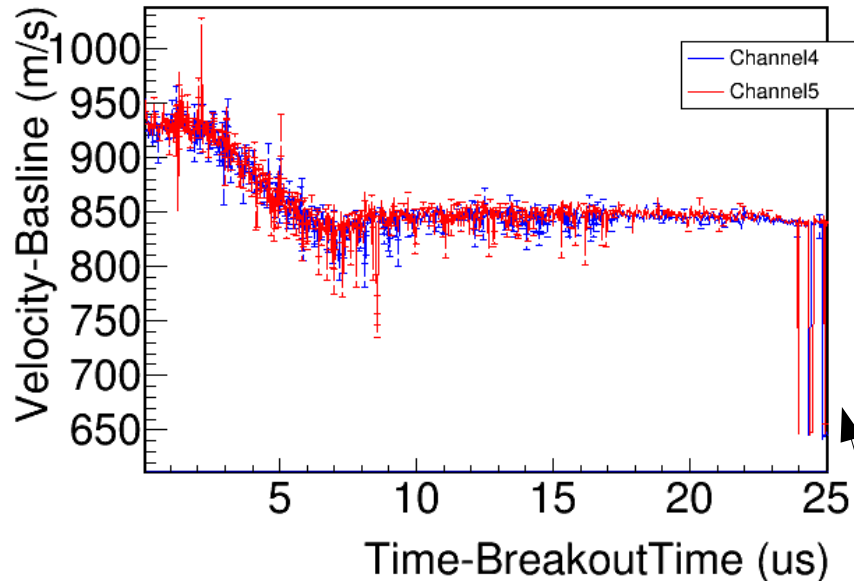


Time(us)	Noise(dB)	Uncert(dB)	TSpeak1	Freq1(GHz)	Uncert(GHz)	Velocity1(m/s)	Uncert(m/s)	Amplitude1(dB)	Uncert(dB)	Width1(m/s)	Uncert(m/s)	TSpeak2	Freq2(GHz)	Uncert(GHz)	Velocity2(m/s)	Uncert(m/s)	Amplitude2(dB)	Uncert(dB)	Width2(m/s)	Uncert(m/s)
175.85	-12.404	0.61744	101.7	4.4581	0.0023107	3477.3	1.8023	24.663	2.6528	6.7865	9.625e-20	25.6	4.203	0.010773	3278.3	8.4032	0.62617	3.1346	18.779	5.7451
175.87	-13.408	0.61887	104.7	4.456	0.0029025	3475.7	2.264	21.884	3.6673	7.4983	1.0136	20.7	4.2037	0.0043376	3278.9	3.3834	4.3059	4.4209	7.619	2.2897
175.9	-12.643	0.61261	81.0	4.4548	0.002313	3474.7	1.8042	19.693	2.7005	6.7863	9.7927e-20	19.5	4.2216	0.024549	3292.9	19.148	-3.3384	3.0927	29.419	12.713
175.93	-13.082	0.61827	76.8	4.4601	0.0024584	3478.9	1.9176	21	2.7241	6.7866	9.8126e-20	24.8	4.2039	0.0034618	3279	2.7002	7.1653	3.1362	6.7864	9.5292e-20
175.95	-13.639	0.61198	78.7	4.4539	0.0022929	3474	1.7884	18.449	2.6975	6.7864	9.8655e-20	33.5	4.2052	0.0044086	3280.1	3.4387	6.2866	3.7395	9.3648	1.8851

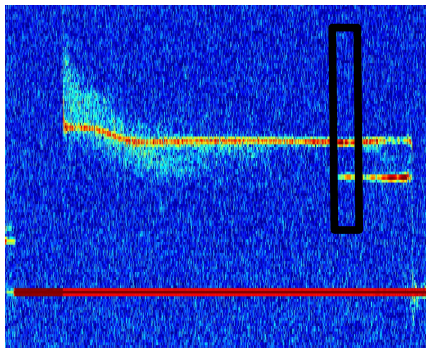
- My output includes (new features in **bold**):
  - Time
  - Noise level **and uncertainty**
  - **Probability that there is a first surface (freq. peak)**
  - Best-fit velocity (from frequency) and uncertainty
  - Amplitude **and uncertainty**
  - **Gaussian width and uncertainty (spread in velocities)**
  - **Probability that there is a second surface (if above 3-sigma)**
    - All the same information about that surface
  - **Probability for a third surface (if above 3-sigma)**
    - etc

# Statistical Analysis on Sample Data

- Smaller error bars and more features

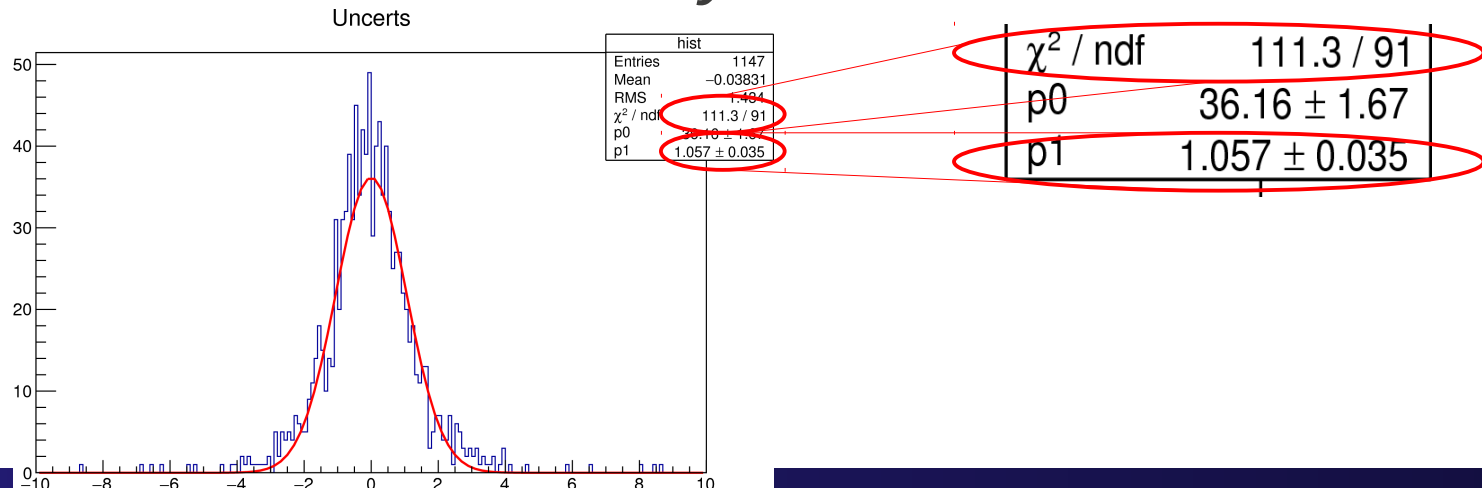


- Can use large Region of Interest (ROI)
  - Finds the second surface
- Error bars are similar size to differences between the channels



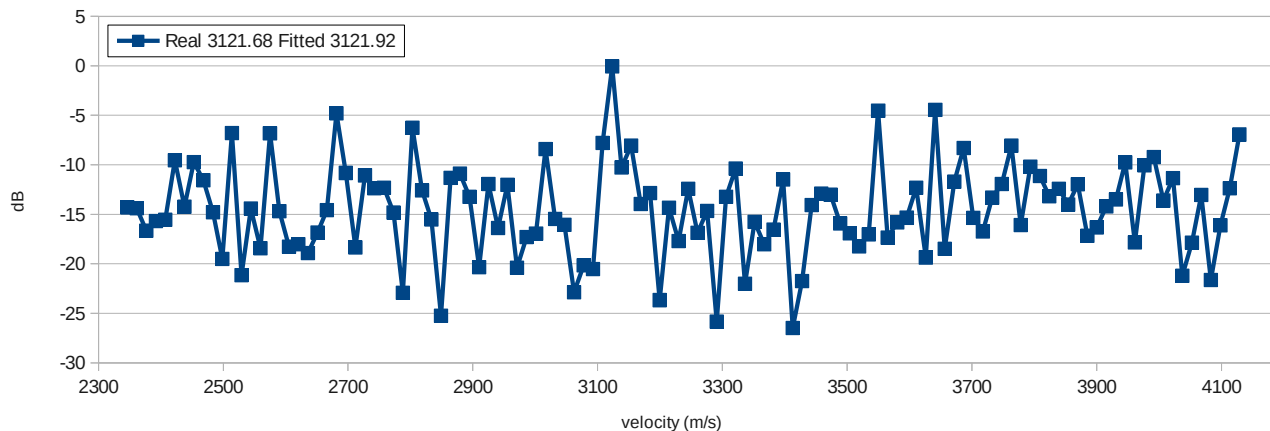
# Likelihood Error Bars are Statistically Correct

- Histogrammed the difference between the channel4 and channel5 fits, divided by the uncertainty
- If the error bars are truly 68% containment (1-sigma), this histogram should be a *Gaussian* with width of *unity*



# Synthetic Data Tests

- Made lineouts with noise randomly thrown on a Gaussian with mean -15dB and width 5dB
- Added peak on top of the noise at known frequency and amplitude





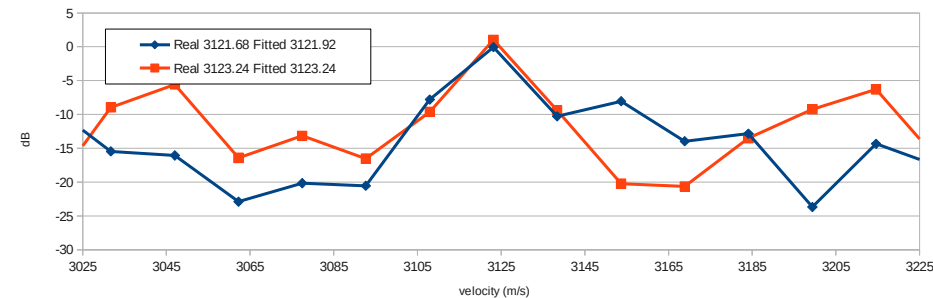
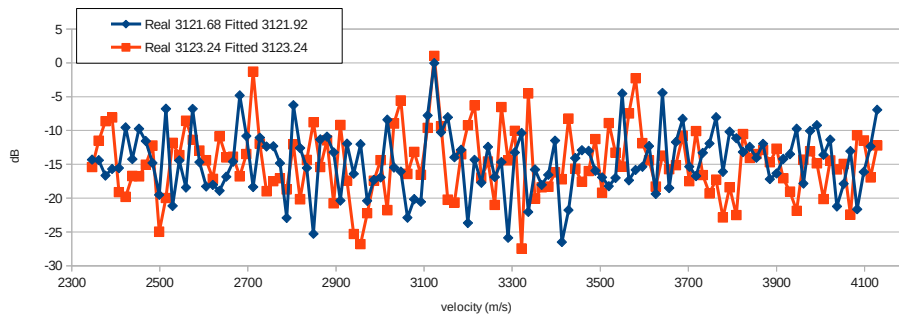
# Synthetic Data – Consistency for a Dim Signal

- Peak with width 7m/s, amplitude 0dB, peak frequency at 4GHz (~3-sigma)
  - Did 100 times to get mean, mean uncert, stdev
- Fitted noise level = **-15.3dB**, uncert = **0.41dB**
  - input = **-15.0dB**, stdev = **0.47dB**
- Fitted velocity = **3099m/s**, uncert = **5.0m/s**
  - input = **3100m/s**, stdev = **4.7m/s**
- Fitted amplitude = **-0.3dB**, uncert = **4.4dB**
  - input = **0.0dB**, stdev = **1.6dB**
- Fitted width = **9.8m/s**, uncert = **3.3m/s**
  - input = **7.0m/s**, stdev = **2.7m/s**

Note: Only 85/100 found the true peak. Others had a fluctuation which was higher than it found

# Synthetic Data – Precision on a Ramped Velocity

- Peak with width 7m/s, amplitude 0dB (~3-sigma)
  - Ramped velocity from 3120-3134m/s in 1.56m/s steps
  - Single velocity bin is 14m/s wide



- Typical error in fitted value is ~2.3m/s
  - A few found false fluctuations, though
- Can find the peak to much better than pixel width
- Can find peak center to much better than peak width

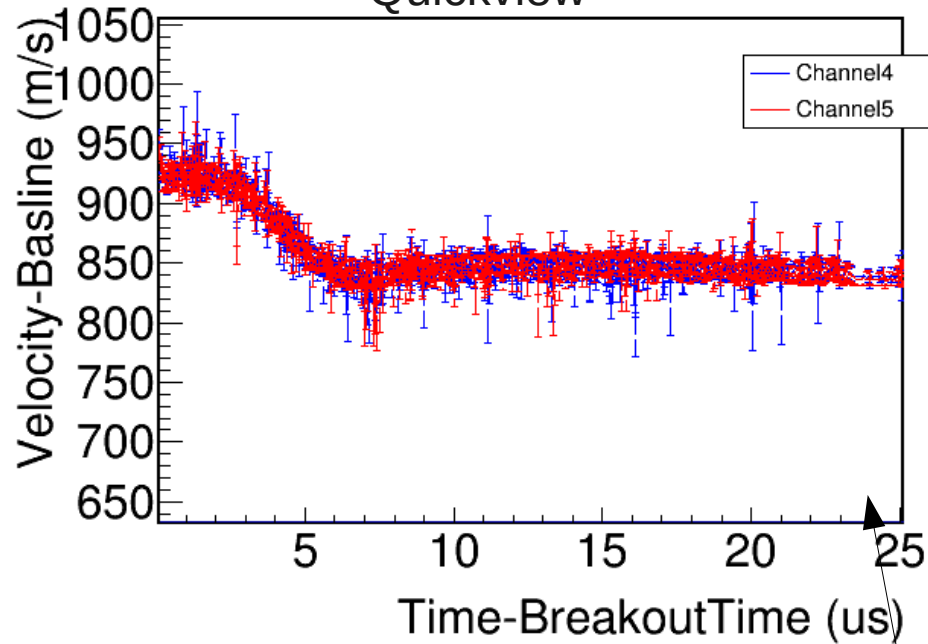
# Summary

- Log-likelihood PDV velocity extractions will:
  - Remove sensitivity to ROI shape/size
  - Get statistically-validated error bars
  - Find features in the spectrogram beyond single surface
- Method is sensitive in noisy regions
  - to better than 5m/s
- Can improve sensitivity to fainter signals by using smaller ROIs (in production)
- Going to apply algorithm to Gemini-Leda-Lyra data

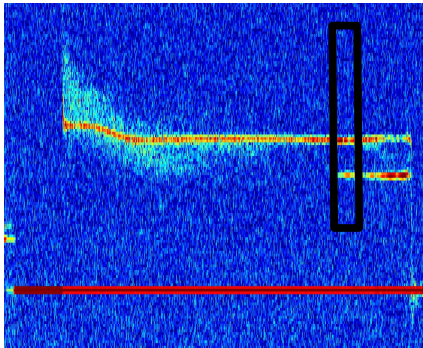
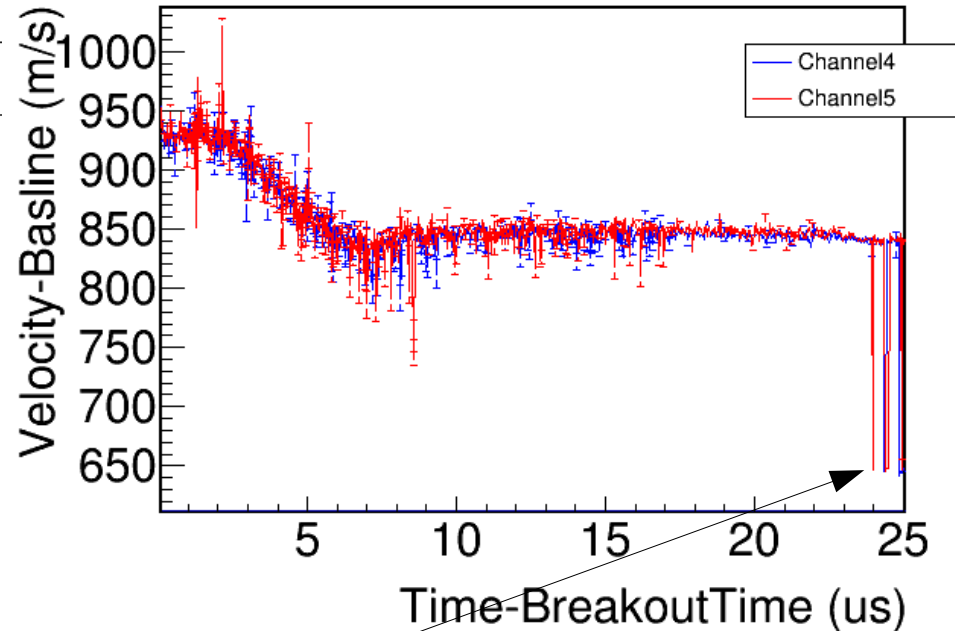
# Backup

# Likelihood vs Moments – New Features

Quickview



Likelihood

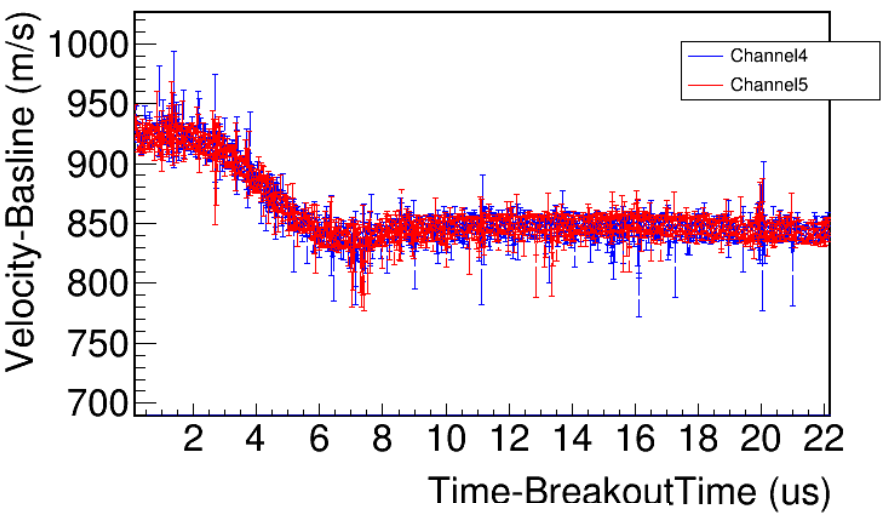


Second peak in this region  
is sometimes brighter

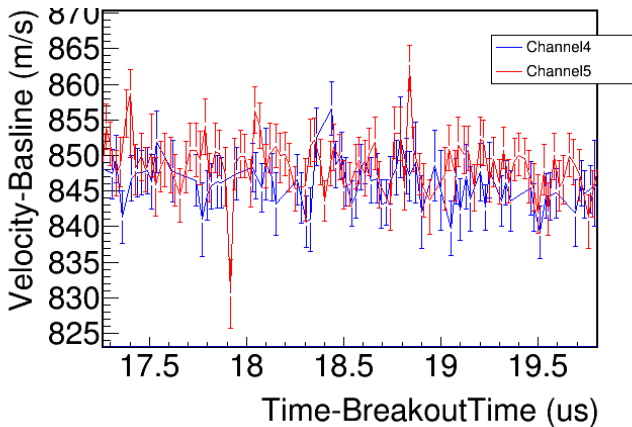
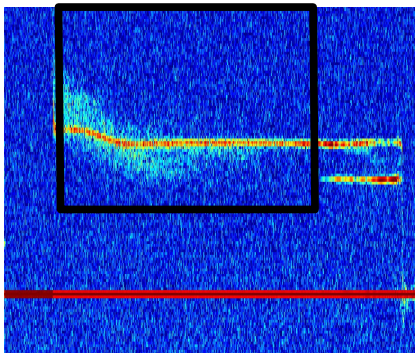
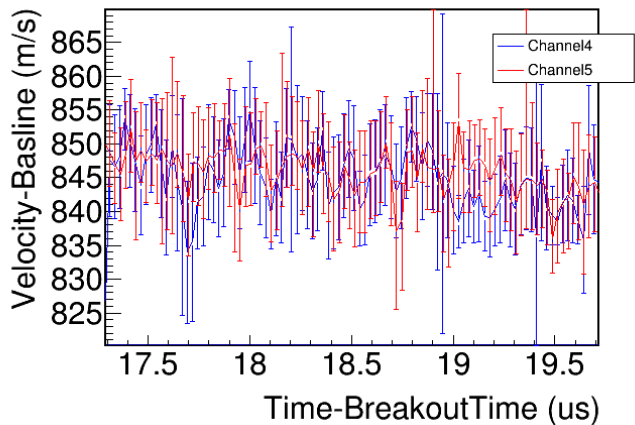
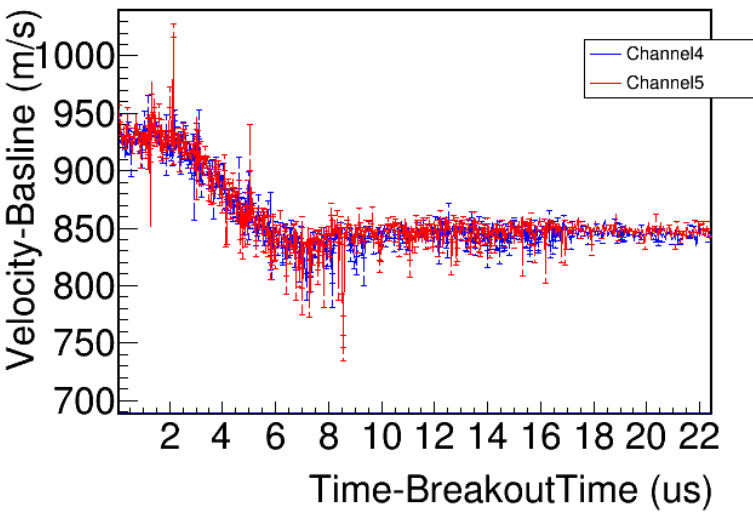


# Likelihood vs Moments – Smaller Error Bars

Quickview

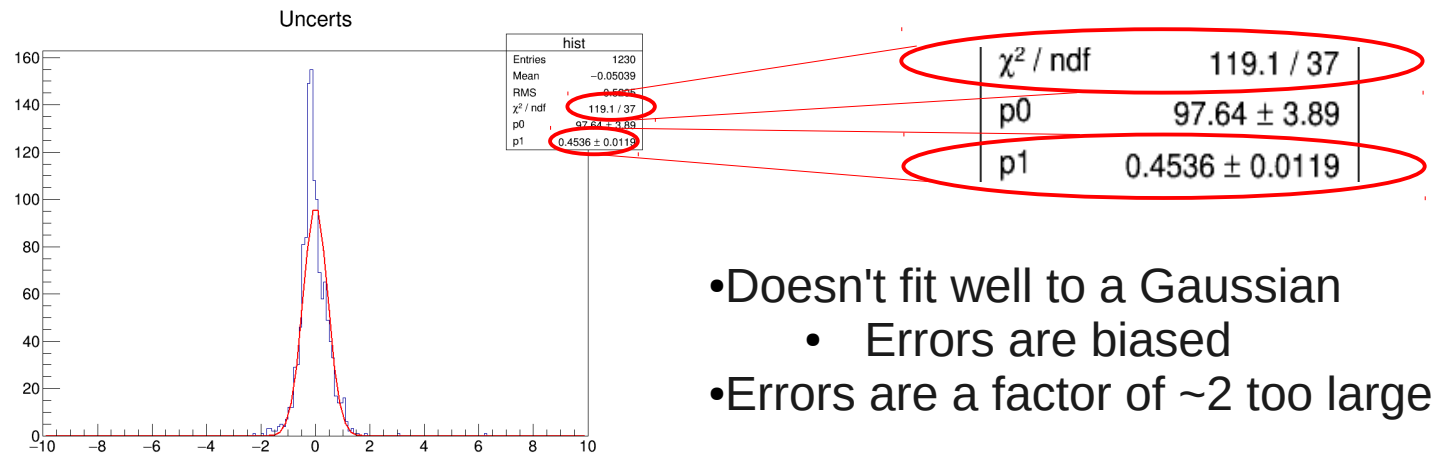


Likelihood



# Error Bars for Moments Analysis

- Histogrammed the difference between the channel4 and channel5 fits, divided by the uncertainty
- If the error bars are truly 68% containment (1-sigma), this histogram should be a *Gaussian* with width of *unity*



# Synthetic Data – Precision on a Ramped Velocity

- Marginal signal, found false peak 3/10 times
- Successful fits show clear linear trend upward
- Can determine velocity to much better than one spectrogram pixel, even for marginal signals

